

## FM IF System Applications

## Overview

The LA1235 is a high integrated IC developed for use in high S/N, low distortion FM IF system applications. This IC features $\mathrm{S} / \mathrm{N}=88 \mathrm{~dB}$, distortion factor $=0.015 \%$ and has almost all functions required for FM tuner IF stage.
The IF amplifier and limiter stage consist of 6 stages of double ended differential amplifier having an excellent AMR, and this stage is followd by the signal meter driver which consists of 4 stages of level detector, thereby creating extended linearity up to strong input. The FM detector stage consists of a double balanced quadrature detector to which a low frequency preamplifire and a muting controller are attached. The muting drive stage consists of an OR circuit for weak signal muting drive output which detects signal intensity and detuning muting drive output which detects $S$ curve DC output and enables the prevention of noise at the time of weak signal and detuning. Further, the weak signal muting drive output circuit contains a Schmitt circuit having hysteresis and enables the prevention of muting malfunction due to amplitude component at the time of weak signal. The AFC output and tuning meter drive stage is of current drive type which makes it possible to adjust AFC sensitivity and muting band width by means of an external resistor, and the built-in tuning meter null (short) circuit foreces the tuning meter to be [0] when th IF amplifier stops working. The IF amplifier stop circuit, being a circuit to stop the FM IF amlifier at the time of AM reception, makes it possible to decrease shock noise due to FM-AM receiving mode switchover.

## Package Dimensions

unit: mm

## 3006B-DIP16



## Functions

- IF amplifier, Limiter.
- Quadrature detection.
- AF preamplifier.
- Signal intesity muting drive output.
- Detuning muting drive output.
- AF signal muting circuit.
- Signal meter drive output.
- AFC, tuning meter drive output.
- IF amplifier stop circuit.
- Tunig meter null circuit.


## Features

- High S/N (88dB typ.).
- Low distortion (0.015\% typ.).
- Weak signal muting dirve output having hysteresis.
- Tuning mete null (short) circuit.
- Signal meter dirve output having wide dynamic range.
- High limiting sensitivity.
- Built-in constant-voltage regulated circuit (Operating voltage : 10 to 14 V ).

Specifications
Maximum Ratings at $\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Ratings | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Maximum supply voltage | $\mathrm{V}_{\text {CC }}$ max | Pin 11 | 16 | V |
| Input voltage | $\mathrm{V}_{\text {IN }}$ | Pins 1 to 2 | $\pm 1$ | Vp-p |
| Supply current | ICC | Pin 11 | 40 | mA |
| Flow-in current | $\mathrm{I}_{5}$ | Pin 5 | 3 | mA |
| Flow-out current | $\mathrm{l}_{10}$ | Pin 10 | 2 | mA |
|  | $\mathrm{I}_{13}$ |  | 2 | mA |
| Allowable power dissipation | Pd max |  | 650 | mA |
| Operating temperature | Topr |  | -20 to +70 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature | Tstg |  | -40 to +125 | ${ }^{\circ} \mathrm{C}$ |

Recommended Operating Conditions at $\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Ratings | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Recommended supply voltage | $\mathrm{V}_{\text {CC }}$ |  | 10 to 14 | V |

Operating Characteristics at $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}}=12 \mathrm{~V}, \mathrm{f}=10.7 \mathrm{MHz}$

| Parameter | Symbol | Conditions | Ratings |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | min | typ | max |  |
| Quiescent current | ICCO | Quiescent |  | 21 | 30 | mA |
| Current drain | ICC | $\mathrm{V}_{\text {IN }}=100 \mathrm{~dB} \mu$ |  | 22 | 31 | mA |
| Detection output | $\mathrm{V}_{\mathrm{O}}$ | $\mathrm{V}_{\mathrm{IN}}=100 \mathrm{~dB} \mu, 400 \mathrm{~Hz}, 100 \%$ mod. | 310 | 430 | 590 | mVrms |
| S/N |  | $\mathrm{V}_{\mathrm{IN}}=100 \mathrm{~dB} \mu, 400 \mathrm{~Hz}, 100 \% \mathrm{mod}$. | 82 | 88 |  | dB |
| -3dB limiting sensitivity | V IN(lim) | $\mathrm{V}_{\mathrm{O}}$ : $-3 \mathrm{~dB}, 400 \mathrm{~Hz}, 100 \% \mathrm{mod}$. |  | 25 | 31 | dB $\mu$ |
| Muting sensitivity | V IN(mute) | $\mathrm{V}_{12}=5.6 \mathrm{~V}, \mathrm{R}_{16}=56 \mathrm{k} \Omega, \mathrm{R}_{15}=50 \mathrm{k} \Omega$ |  | 40 | 50 | dB $\mu$ |
| Muting attenuation | mute(att) | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=100 \mathrm{~dB} \mu, 400 \mathrm{~Hz}, 100 \% \mathrm{mod} . \\ & \mathrm{V}_{5}=3.5 \mathrm{~V} \end{aligned}$ | 80 | 100 |  | dB |
| Muting bandwidth | BW(mute) | $\mathrm{V}_{1 \mathrm{~N}}=100 \mathrm{~dB} \mu, \mathrm{~V}_{12}=3 \mathrm{~V}$ | 120 | 200 | 330 | kHz |
| Muting driving output | $\mathrm{V}_{12}$ (1) | Quiescent | 5.6 | 6.2 | 6.8 | V |
|  | $\mathrm{V}_{12}(2)$ | $\mathrm{V}_{\text {IN }}=100 \mathrm{~dB} \mu$ |  | 0 | 0.3 | V |
| Total harmonic distortion | THD | $\mathrm{V}_{\mathrm{IN}}=100 \mathrm{~dB} \mu, 400 \mathrm{~Hz}, 100 \% \mathrm{mod}$. |  | 0.015 | 0.05 | \% |
| AM supperssion ratio | AMR | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=80 \mathrm{~dB} \mu, \mathrm{FM}=400 \mathrm{~Hz}, 100 \% \text { mod, } \\ & \mathrm{AM}=1 \mathrm{kHz}, 30 \% \text { mod. } \end{aligned}$ | 45 | 60 |  | dB |
| Signal meter driving output | $\mathrm{V}_{13(1)}$ | Quiescent |  | 0 | 0.1 | V |
|  | $\mathrm{V}_{13(2)}$ | $\mathrm{V}_{\text {IN }}=35 \mathrm{~dB} \mu$ |  | 0.1 | 0.5 | V |
|  | $\mathrm{V}_{13}$ (3) | $\mathrm{V}_{\text {IN }}=70 \mathrm{~dB} \mu$ | 1.3 | 2.0 | 2.9 | V |
|  | $\mathrm{V}_{13(4)}$ | $\mathrm{V}_{\mathrm{IN}}=100 \mathrm{~dB} \mu$ | 2.2 | 3.5 | 5.0 | V |
| Offset voltage | $\mathrm{V}_{6-10}$ | Quiescent, pin 6 to 10 | -0.8 | 0 | +0.8 | V |
|  | $\mathrm{V}_{7-10}$ | Quiescent, pin 7 to 10 | -0.4 | 0 | +0.4 | V |
| Tuning meter null voltage | $\mathrm{V}_{7-10 \text { (null) }}$ | $\mathrm{V} 5=7.5 \mathrm{~V}$, pin 7 to 10 | -50 | +5 | +50 | mV |
| IF-off voltage | $\mathrm{I}_{15 \text { (IF off) }}$ | $\mathrm{V}_{2-3}=1 \mathrm{~V}$ | 5.6 |  | 7.5 | V |

Reference Pin Voltage

| Pin No. | Condition | Pin voltage (V) |
| :---: | :---: | :---: |
| $\mathrm{V}_{1}$ |  |  |
| $\mathrm{~V}_{2}$ |  | 2.6 |
| $\mathrm{~V}_{3}$ |  | 6.2 |
| $\mathrm{~V}_{6}$ |  | 5.9 |
| $\mathrm{~V}_{7}$ |  | 6.2 |
| $\mathrm{~V}_{8}$ | Quiescent |  |
| $\mathrm{V}_{10}$ |  | 0 |
| $\mathrm{~V}_{12}$ |  |  |
| $\mathrm{~V}_{13}$ |  |  |
| $\mathrm{~V}_{15}$ |  |  |
| $\mathrm{~V}_{16}$ |  |  |



## Test Circuit



- Setting of muting sensitivity, hysteresis width (Refer to the equivalent circuit block diagram and application circuit). Muting sensitivity and hysteresis width are set arbitarily by varying resistors $\mathrm{R}_{204}$ and $\mathrm{R}_{205}$ connected to pins 15 and 16, respectively. Muting sensitivity is set by varying $\mathrm{R}_{204}$; and if $\mathrm{R}_{204}$ is made larger, muting sensitivity will shift to the weak signal side. Hysteresis width is set by varying $\mathrm{R}_{205}$; and if $\mathrm{R}_{205}$ is made larger, hysteresis width will narrow. Next, how to set muting sensitivity is concretely described as follows. In case of using $\mathrm{R}_{204}=50 \mathrm{k} \Omega$ (semifixed resistor) and $\mathrm{R}_{205}=56 \mathrm{k} \Omega$, the upper limit of current $\mathrm{I}_{16}, 50 \mu \mathrm{~A}$, delivered from the signal meter driver at which muting is turned ON is obtained from the first quadrant of Table for muting adjustable lower limit calculation. Muting is turned ON at $\mathrm{I}_{16} \leq 50 \mu \mathrm{~A}$. If $\mathrm{I}_{16} \leq 50 \mu \mathrm{~A}$, muting is already turned ON at a point of input being stronger than the setting input and it is impossible to adjust muting at the setting input. Therefore, $\mathrm{I}_{16}>50 \mu \mathrm{~A}$ is required at the setting input. The input at which a sample with a small $\mathrm{I}_{16}$ output meets $50 \mu \mathrm{~A}$ is obtained as $\mathrm{V}_{\mathrm{IN}}=47 \mathrm{~dB} \mu$. This input is the maximum value of muting sensitivity, that is to say, the lower limit at with muting can be set. The data for sample with a Small $\mathrm{I}_{16}$ shown in this Table is colose to the minimum value, but since samples with values less than this munimum value may occur, a margin of some $\mathrm{dB} \mu$ must be allowed. From the above, the minimum value for muting setting (muting ON input) becomes $50 \mathrm{~dB} \mu$ for $\mathrm{R}_{204}$ (semifixed resistor) $=50 \mathrm{k} \Omega$ and $\mathrm{R}_{205}=56 \mathrm{k} \Omega$.

Muting sensitivity setting by means of $\mathrm{R}_{204}$


Hysteresis width setting by means of $\mathrm{R}_{205}$


Table for muting adjustable lower limit calculation


Muting Sensitivity Characteristic


- Setting of muting circuit constnats

Drive current to be output at muting drive output pin 12 is 0.75 mA typ., but approximately 0.4 mA may be caused by variations in characteristic or changes in temperature (smaller at higher temperatures). It is desirable to design the circuit so that the total current to be output from pin 12 at the time of muting ON does not exceed 0.35 mA . When driving the muting circuit of the LA1235, the muting drive current (input current at pin 5) must be considered besides this total output current. The muting drive current of the LA1235 is 0.2 mA max.
Thus, the muting constants are obrained as follows. If the muting drive current is $\mathrm{I}_{\mathrm{R} 207} \geq 0.2 \mathrm{~mA}, \mathrm{R}_{207} \leq 14 \mathrm{k} \Omega$ occurs and the total current It is shown

## Muting Circuit

 by the following expression.

$$
\mathrm{It}=\mathrm{I}_{\mathrm{R} 206}+\mathrm{I}_{\mathrm{R} 207}=\frac{6.2 \mathrm{~V}}{\mathrm{R}_{206}}+\frac{4.8 \mathrm{~V}}{\mathrm{R}_{206}+10 \mathrm{k} \Omega} \quad(10 \mathrm{k} \Omega: \text { Input resistance at pin 5, Refer to the above figure. })
$$

If $R_{207}=10 \mathrm{k} \Omega$ is taken with the variation s in voltage $\mathrm{V}_{12}$ at pin 12 and input resistance $10 \mathrm{k} \Omega$ at pin 5 considered, $R_{206} \approx 56.4 \mathrm{k} \Omega$ is obtained, and then $\mathrm{R}_{206}=68 \mathrm{k} \Omega$ and $\mathrm{R}_{207}=10 \mathrm{k} \Omega$ are obtained.

- Setting of $\mathrm{C}_{112}$ (Capacitance between pin 12 and ground)
$\mathrm{C}_{112}$ influences $\mathrm{S} / \mathrm{N}$ and muting attenuation. $\mathrm{S} / \mathrm{N}$ is improved 0.5 to 2.0 dB by changing $\mathrm{C}_{112}$ from $1 \mu \mathrm{~F}$ to $100 \mu \mathrm{~F}$. Muting attenuation becomes as shown in Mute (att) - fm (next page) characteristic. This phenomenon occurs because the output at pin 7 appears at pin 6 through pin 10 and capacitance $C_{110}$ between pin 7 and ground also exerts influence. The relation between muting attenuation andC $\mathrm{C}_{110}$ is such that if $\mathrm{C}_{110}=2.2 \mu \mathrm{~F}$ and $\mathrm{C}_{112}=220 \mu \mathrm{~F}$, attenuation at modulation frequency 100 Hz becomes -80 dB .


## AF Output Circuit





## Sample Printed Circuit Pattern



Equivalent Circuit Block Diagram and Sample Application Circuit


## Description of external parts

| Part No. | Function | Effect |  |
| :---: | :---: | :---: | :---: |
|  |  | If decreased | If increased |
| R201 | Input resistance (Rg) | Causes matching wigh circuit of prece | ding stage. |
| $\begin{aligned} & \text { R202 } \\ & \text { R203 } \end{aligned}$ | S meter adjust | Current drain increases. (Observe max. rating). | S meter pointer is off zero point. (In case of voltage drive type). |
| R204 | Muting sensitivity adjust | Muting sensitivity shifts to weak input side. |  |
| R205 | Hysterisis adjunt | Large hysteresis. | Small hysteresis. |
| R206 | Muting drive circuit load | Insufficient drive of detuning muting. | When driveing muting of LA3390 (MPX), make less than $200 \mathrm{k} \Omega$ to prevent malfunction. |
| R207 | Muting time constant | Abnormal detuning muting attenuation waveform and abnormal sound at the time of low frequency modulation. | Muting response delay. |
| R208 | IF-off voltage applying resistnace | Large flow-in current at pin 5 (Observe max. rating). | IF-off does not occur. (IF-off voltage $\geq 7.5 \mathrm{~V}$ ). |
| $\begin{aligned} & \text { R209 } \\ & \text { R210 } \end{aligned}$ | AFC, detuning muting band width, tuning meter deflection adjust | Large detuning muting bandwidth. | Small detuning muting bandwidth. |
| R211 | Detection coil damping | Small detection output. | Large detection output. |
| R212 | S curve linearity correction | Find such a value as to cause minimu | $m$ distortion (THD). |
| $\begin{aligned} & \text { C101 } \\ & \text { C102 } \\ & \text { C103 } \end{aligned}$ | IF amplifier bypass | Unstable IF amplifier. |  |
| C104 | S meter output bypass | IF system may be unstable. |  |
| $\begin{aligned} & \text { C105 } \\ & \text { C106 } \end{aligned}$ | Muting drive output bypass | If low frequency AM compoent is generated in IF signal, weak signal muting flutters. | Muting response delay. |
| $\begin{aligned} & \text { C107 } \\ & \text { C108 } \end{aligned}$ | Muting drive output smooth | Abnormal detuning muting attenuation waveform and abnormal sound at the time of low frequency modulation. | Muting response delay. |
| C109 | AF output LPF | Unstable IF system. | With MPX connected, separation worsens. |
| C110 | AFC output LPF | Muting attenuation worsens and detuning muting bandwidth narrows. | Detunig muting response delay. |
| $\begin{aligned} & \text { C111 } \\ & \text { C112 } \end{aligned}$ | Constant voltage circuit smooth | S/N, muting attenuation worsen. |  |
| C113 | Power supply bypass | Unstable IF system. |  |
| L1 | Power supply choke | Unstable IF system. |  |

## Proper cares in using IC

- Connect the ground side of bypass capacitors of pins 2, 3 to an area close to pin 4 .
- Connect the ground side of bypass capacitors of pins $6,7,10,13,16$ to an area close to pin 14 .
- Use the shortest possible wires for detection coil-to-pins 8, 9, 10 connection.
- Pin 13, being used for signal meter drive output, can be also used multipath detection because IF signal envelope detected is output at this pin.

Coil specifications

| Supplier | Coil name | Damping resistance |  | Remarks |
| :---: | :--- | :---: | :---: | :--- |
|  |  | $R 211$ | $R 212$ |  |
| Sumida | 235S01 | $4.7 \mathrm{k} \Omega$ | $3.3 \mathrm{k} \Omega$ | Containing fixed inductance $26 \mu \mathrm{~F}$. |
|  | SNY-074-1919A | $7.5 \mathrm{k} \Omega$ | $2.4 \mathrm{k} \Omega$ | Containing fixed inductance $26 \mu \mathrm{~F}$. <br>  |
|  |  |  | (Improvement in temperature characteristic). |  |
| Toko | Q228CEL-1077B | $13 \mathrm{k} \Omega$ | $3.0 \mathrm{k} \Omega$ | Containing fixed inductance |




$\mathrm{V}_{\mathrm{IN}(\text { mute })}$ - Ta





Tuning Error - Ta





## Cain distribution of application circuit

If IC anone is operated without front end, the tuning meter deflects toward plus side at the time of no input. This phenomenon is caused by the fact that the noise component to be applied to the quadrature multiplication circuit is not syummetric with respect to 10.7 MHz but is shifted toward lower frequency side because the frequency characteristic of IF amplifier attenuates at high frequencies and the phase shift circuit is of low-pass type. If the formt end is attached and the noise which passes through the narrowband filter of IF stage and spreads symmetrically with respect to 10.7 MHz is stronger than the noise generated inside the IC, the tuning meter reads 0 .As the gain of the front end is decreased, input limiting sensitivity and usable sensitivity worsen abruptly. This phenomenon is caused by the fact that since the tuning meter is set to 0 at the time of no input the tuning point of the quadrature circuit must be shifted toward lower frequency side than 10.7 MHz and the demodulation output waveform is deformed asymmetrically at an input in the vicinity of usable sensitivity. However, if the gain of the front end is too increased, the signal meter poiter does not return to zero point at the time of no signal.

## Sample Application Circuit



Front end gain distribution
Unit (resistance : $\Omega$, capacitance : F)


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